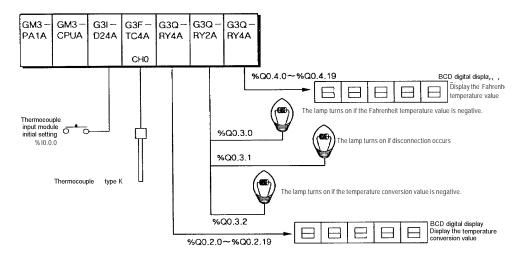
Chapter 5. PROGRAMMING

5.1 A program for Converting a Detected Temperature Value(°C) into Fahrenheit(°F) and Outputting as a BCD Value

1) System Configuration



2) Initial settings

- (1) Specifying the used channel: channel 0
- (2) Specifying the type of the thermocouple: Type K

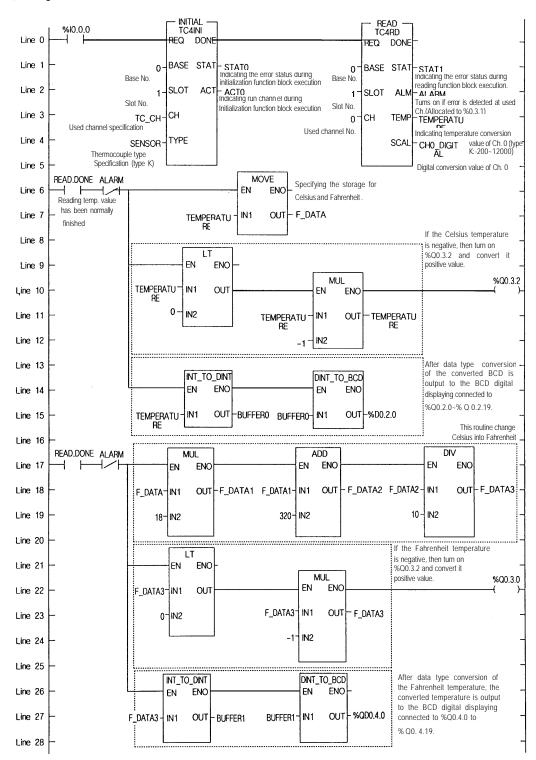
3) Expression for conversion of a temperature conversion value into a Fahrenheit temperature(° F)

:. If the Fahrenheit temperature displayed on the BCD digital display is displayed with the value of 'detected Fahrenheit temperature (F) \times 10', then it is needed to process the expression "temperature conversion value \times 18 + 320".

4) Program Description

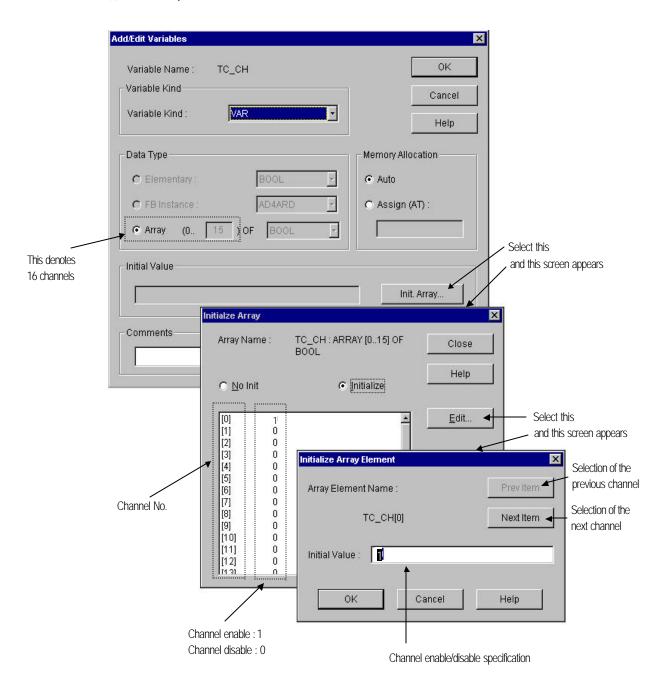
- (1) If %10.0.0 turns on then the thermocouple input module would be initialized.
- (2) The temperature conversion value is displayed on the BCD digital display of %Q0.2.0 to %Q0.2.19. If the value is negative the ramp %Q0.3.2 will turn on.
- (3) After the conversion of the temperature conversion value into a Fahrenheit temperature (°F), it will be displayed on the BCD digital display of %Q0.4.0 to %Q0.4.19. If it is negative the ramp %Q0.3.0 will turn on.
- (4) If disconnection is detected during conversion of temperature of the channel 0, the ramp %Q0.3.1 will turn on.

5) Program

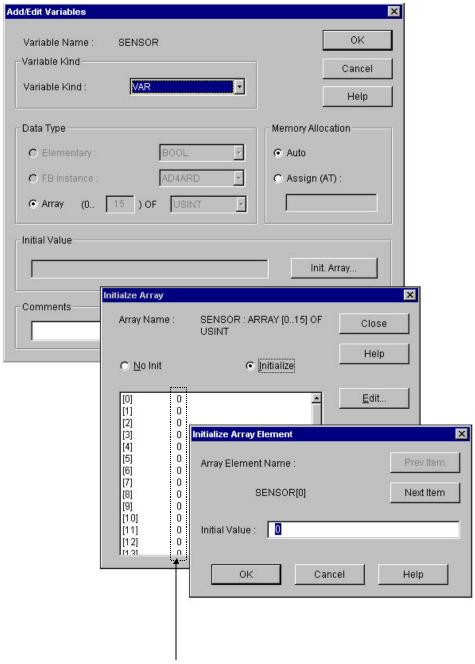


6) Initial Value Setting Method for I/O Variables

(1) Channel Specification



(2) Thermocouple Type Specification



Thermocouple type specification

Input specification No.	Sensor type	Temperature range
0	K	-200.0 to 1200.0°C
1	J	-200.0 to 800.0°C
2	E	-150.0 to 600.0°C
3	T	-200.0 to 400.0°C
4	В	400.0 to 1800.0°C
5	R	0.0 to 1750.0 ℃
6	S	0.0 to 1750.0 °C

7) I/O Variables Used in the Program

Variable Name	Var_Kind	Data Type	(AT Address) (Initial Value)
ACT0	: VAR	: ARRAY [015] OF BOOL	
ALARM	: VAR	: BOOL	AT %Q0.3.1
BUFFER0	: VAR	: DINT	
BUFFER1	: VAR	: DINT	
CH0_DIGITAL	: VAR	: INT	
F_DATA	: VAR	: INT	
F_DATA1	: VAR	: INT	
F_DATA2	: VAR	: INT	
F_DATA3	: VAR	: INT	
INITIAL	: VAR	: FB Instance	$A := \{ 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, $
READ	: VAR	: FB Instance	
SENSOR	: VAR	: ARRAY [015] OF USINT	
STAT0	: VAR	: USINT	
STAT1	: VAR	: USINT	
TC_CH	: VAR	: ARRAY [015] OF BOOL	$:=\{1,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0$
TC_INI	: VAR	: FB Instance	
TEMPERATURE	: VAR	: INT	

5.2 A program for Magnitude Comparison of a Detected Temperature Value

1) System Configuration

GM3- PA1A	GM3 – CPUA	G3F – TC4A	G3Q – RY2A	

2) Initial Settings

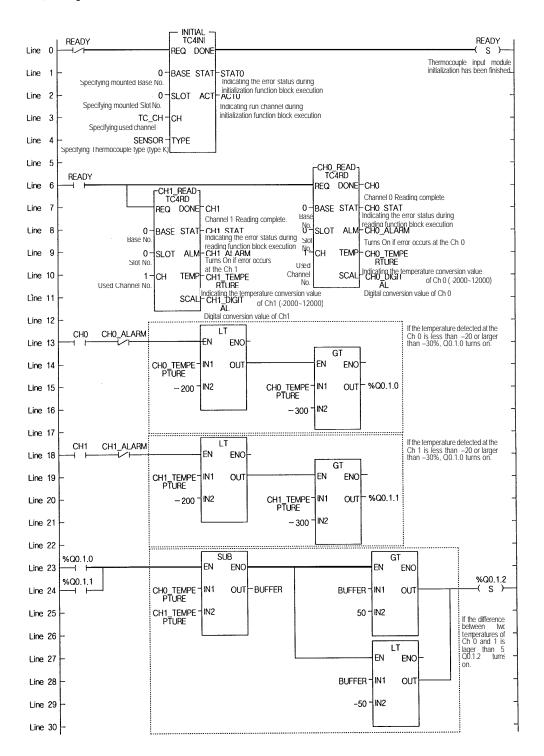
(1) Used Channel : Channel 0 and 1

(2) Thermocouple type specification: Type K

3) Program Descriptions

- (1) If the temperature that is input through the channel 0 of the thermocouple input module is less than -20°C or larger than -30°C , %Q0.1.0 turns on.
- (2) If the temperature that is input through the channel 1 of the thermocouple input module is less than -20°C or larger than -30 °C, %Q0.1.1 turns on.
- (3) If the difference between the two temperatures that are input through the channel 0 and 1 is larger than 5°C, %Q0.1.2 turns on.

4) Program

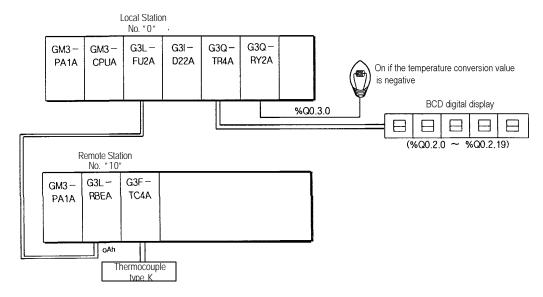


5) I/O Variables Used in the Program

Variable Name	Var_Kind	Data Type	(AT Address)	(Initial Value)
ACT0	: VAR	: ARRAY [015] OF BOOL		
BUFFER	: VAR	: INT		
CH0	: VAR	: BOOL		
CH0_ALARM	: VAR	: BOOL		
CH0_DIGITAL	: VAR	: INT		
CH0_READ	: VAR	: FB Instance		
CH0_STAT	: VAR	: USINT		
CH0_TEMPERTURE	: VAR	: INT		
CH1	: VAR	: BOOL		
CH1_ALARM	: VAR	: BOOL		
CH1_DIGITAL	: VAR	: INT		
CH1_READ	: VAR	: FB Instance		
CH1_STAT	: VAR	USINT		
CH1_TEMPERTURE	: VAR	: INT		
INITIAL	: VAR	: FB Instance		
READY	: VAR	: BOOL		
SENSOR	: VAR	: ARRAY [015] OF USINT	$:= \{0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,$	0, 0, 0, 0, 0, 0, 0, 0, 0 }
STAT0	: VAR	: USINT		
TC_CH	: VAR	: ARRAY [015] OF BOOL	$:=\{1,1,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0$	0, 0, 0, 0, 0, 0, 0, 0, 0 }

5.3 A Program Used When Mounting a Thermocouple Input Module onto the Remote I/O Station

1) System Configuration



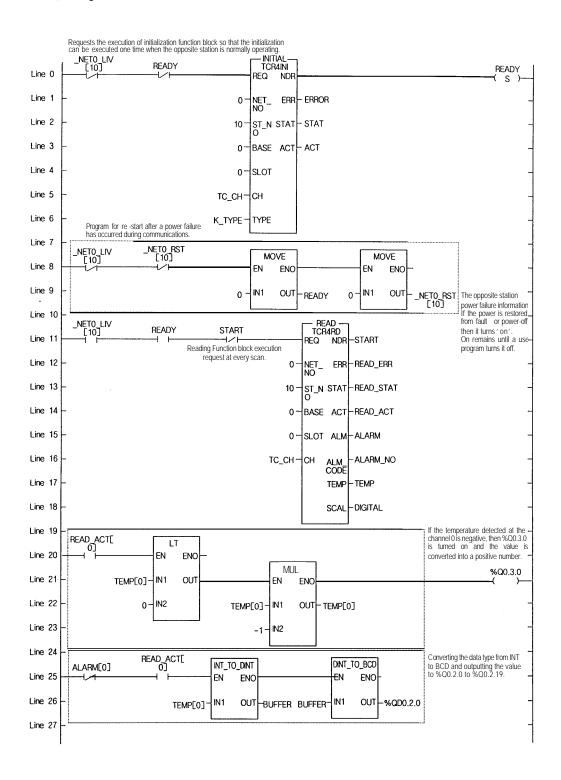
2) Initial Settings

(1) Specifying used channel : Channel 0(2) Specifying thermocouple type: Type K

3) Program Description

- (1) _NETO_LIV[10] : Turns "On" if the local normally communicates with the remote. _NETO_RST[10] : Turns "On" if communications error or power failure occurs. The user has to turn it off forcedly when the normal state has been restored.
- (2) If the temperature conversion value is negative, %Q0.3.0 will be turned "Orr" and the value will be changed into a positive value.
- (3) If no error has been occurred during execution of the reading function block, the temperature conversion value will be output to " %QD0.2.0".

4) Program



5) I/O Variables Used in the Program

Variable Name	Var_Kind	Data Type	(AT Address)	(Initial Value)
ACT0	: VAR	: ARRAY [015] OF BOOL		
BUFFER	: VAR	: INT		
CH0	: VAR	: BOOL		
CH0_ALARM	: VAR	: BOOL		
CH0_DIGITAL	: VAR	: INT		
CH0_READ	: VAR	: FB Instance		
CH0_STAT	: VAR	: USINT		
CH0_TEMPERTURE	: VAR	: INT		
CH1	: VAR	: BOOL		
CH1_ALARM	: VAR	: BOOL		
CH1_DIGITAL	: VAR	: INT		
CH1_READ	: VAR	: FB Instance		
CH1_STAT	: VAR	USINT		
CH1_TEMPERTURE	: VAR	: INT		
INITIAL	: VAR	: FB Instance		
READY	: VAR	: BOOL		
SENSOR	: VAR	: ARRAY [015] OF USINT	$:= \{0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,$	0,0,0,0,0,0,0,0,0,0
STAT0	: VAR	: USINT		
TC_CH	: VAR	: ARRAY [015] OF BOOL	$:=\{1,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0$	0, 0, 0, 0, 0, 0, 0, 0, 0 }